# Strategies for Achieving Sub-micron Orbit Stability at SLS

- sub-micron - to which level?
- elimination of vibration sources (as far as possible)
- improvements of measurement systems (BPM electronics etc.)
- low gap BPM, matching circuits ?
- integration of HLS, HPS, POMS
- integration of X-Ray BPMs
- discrimination of noise sources in storage ring and experiments
- passive and/or active vibration damping at the experiments

# Stability Requirements I

## General statement of users:

**Source fluctuations should be one order of magnitude below the resolution and detectivity of experimental stations.**

## Experiments have achieved:

- **photon energy resolution of $10^{-4}$ to $10^{-5}$**
- **detectivity resp. S/N-ratios on the sample of $10^{-3}$ to $10^{-4}$**

## This translates into reqiurements for:

### Angular Stability:

**(assuming planar crystal monochromator)**

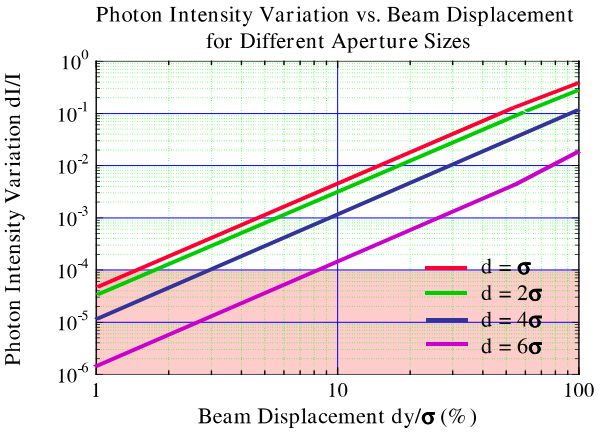
**Bragg's law:** $\frac{\Delta E_{ph}}{E_{ph}} = \frac{\Delta\Theta}{\Theta_B}$

**with Bragg angle** $\Theta_B \sim 5° - 45°$ **(90 - 800 mrad)**

$\Delta\Theta_{beam} < 1\ \mu rad$

### Position Stability:

**(assuming gaussian beamshapes)**




$\Delta x_{beam}, \Delta y_{beam} < \sigma / 10$

**for low ε and low beta machines: < 1 μm**

# Requirements for Achieving Sub-micron Orbit Stability at SLS

- original requirement:
  position RMS < 1/10th of $_{beam}$
- design:
  1% coupling @ short straight IDs
  ⇒ 7 m beam size
  ⇒ orbit stability < 0.7 m RMS
- achieved coupling: 0.3 - 0.7%
  ⇒ 4 - 6 m beam size
  ⇒ orbit stability < 0.5 m RMS

# Improvements of Readout Electronics

## BPM Electronics - RF Front End:

- present hw:
  analogue down-conversion from
  500 MHz to IF (36.029 MHz)

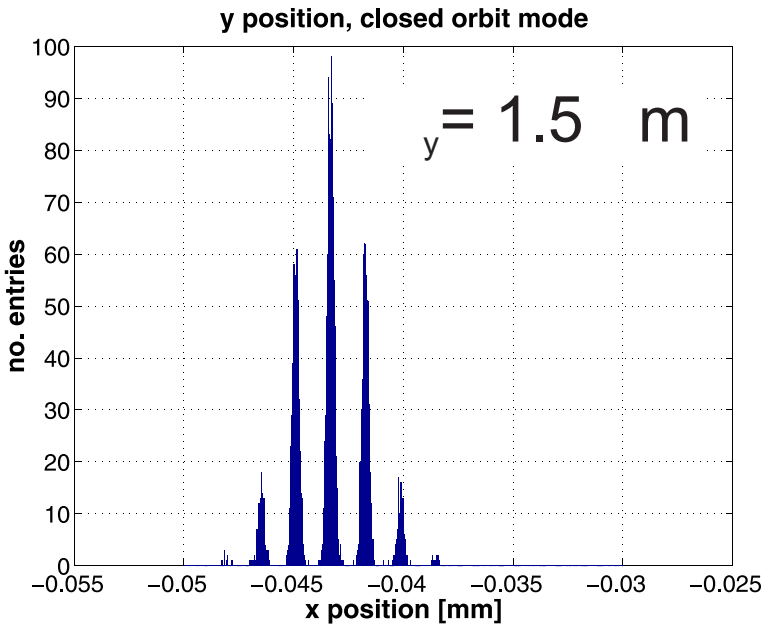
- future replacement (?) of RF FE
  with "passive" module (without
  mixers)
  ⇒ direct sampling of 500 MHz and
  digital down-conversion/decimation
  to base band
  ... to be evaluated

- in general:
  reduce noise sources in RF FE
  through reduction of active
  elements (mixers, amplifiers, ...)

# Improvements of Readout Electronics

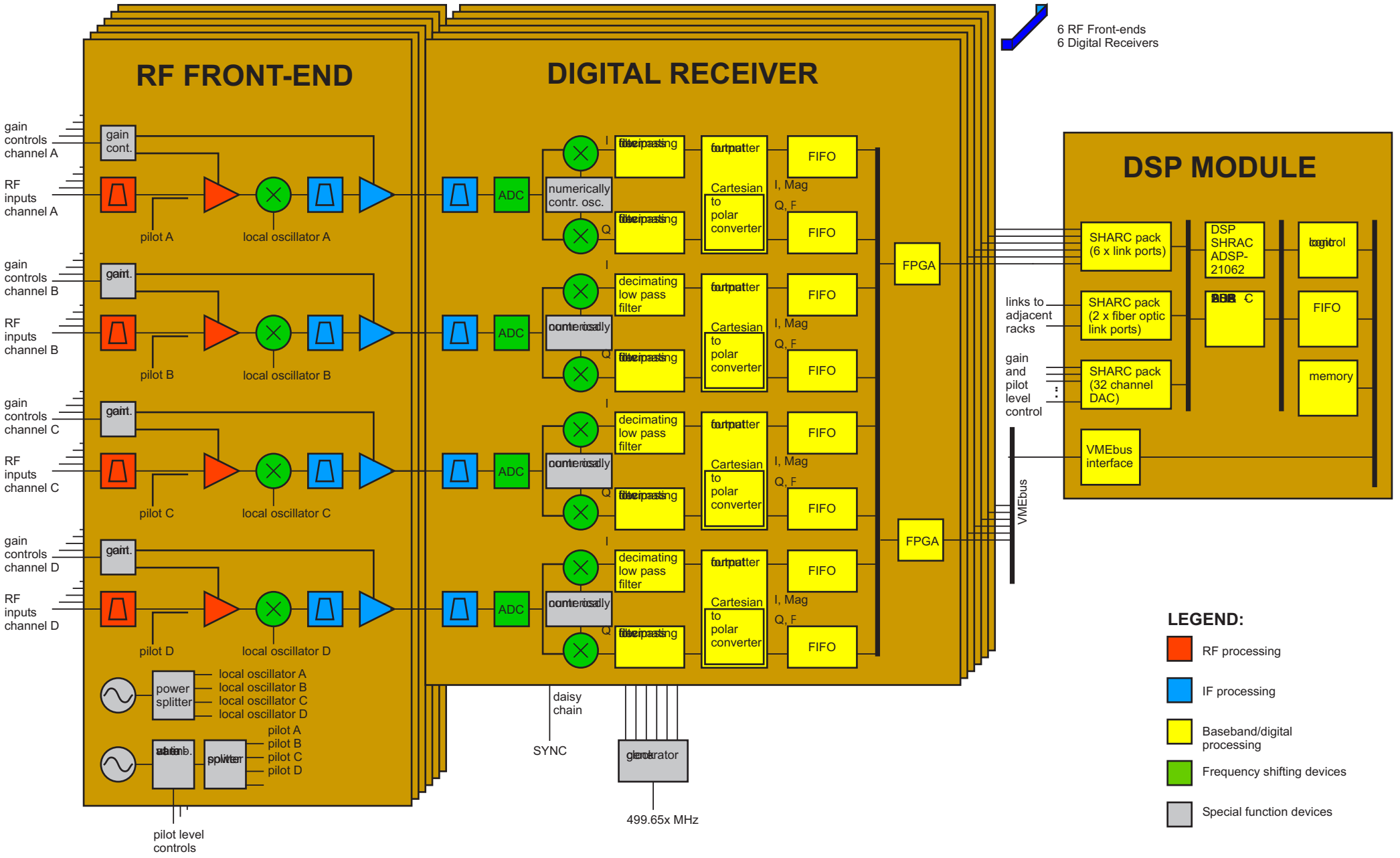
## BPM Electronics - Digital Receiver:

- possible upgrade from 12bit ADC to 14 bit
- resolve signal attenuation in digital down converter by internal gain control




- optimize digital filters (bandwidth versus resolution)

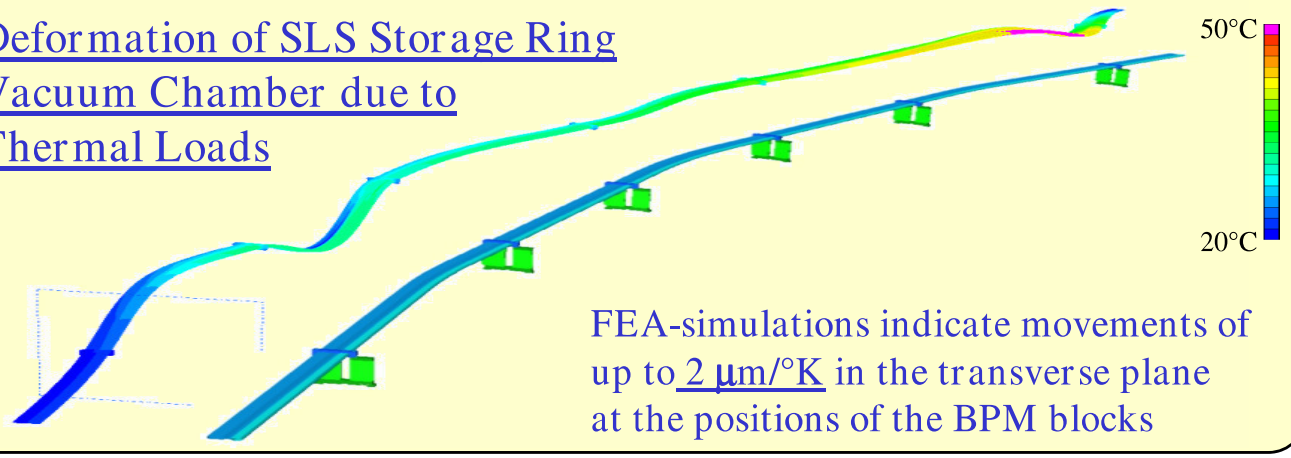
# DIGITAL BEAM POSITION MONITORING SYSTEM (DBPM)



Stability and Dynamic Alignment at SLS

# Mechanical Position Monitoring System (POMS)

## Deformation of SLS Storage Ring Vacuum Chamber due to Thermal Loads

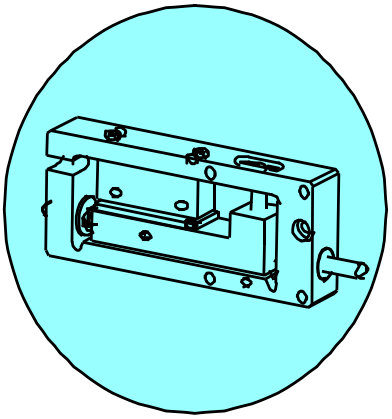


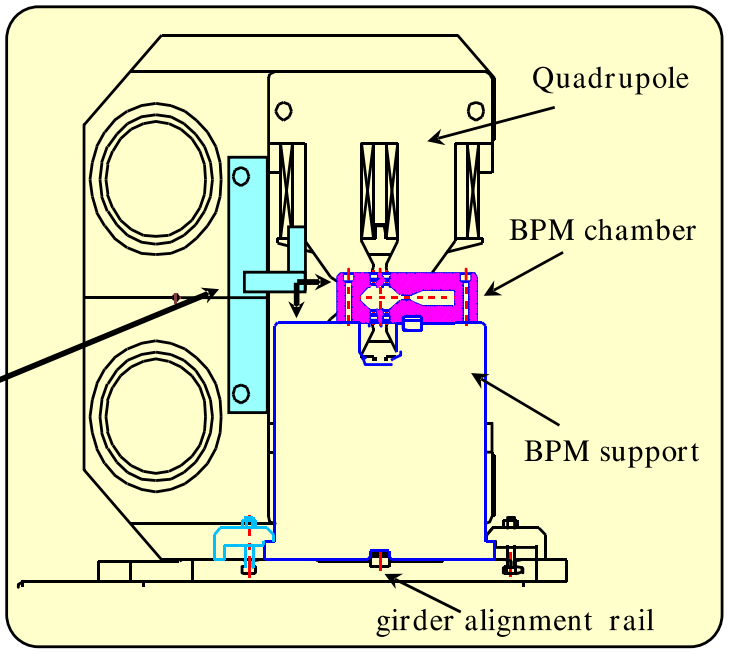

FEA-simulations indicate movements of up to 2 µm/°K in the transverse plane at the positions of the BPM blocks

## POMS System

- Dial gauges sense transverse movements of BPM block in reference to adjacent quadrupole magnets.
- Linear encoders of type Renishaw RGH24Z50A00A with 0.5 µm resolution are used as sensing devices.
- Complete integration into EPICS control system through serial SSI-interface and 32 channel VME-SSI card.

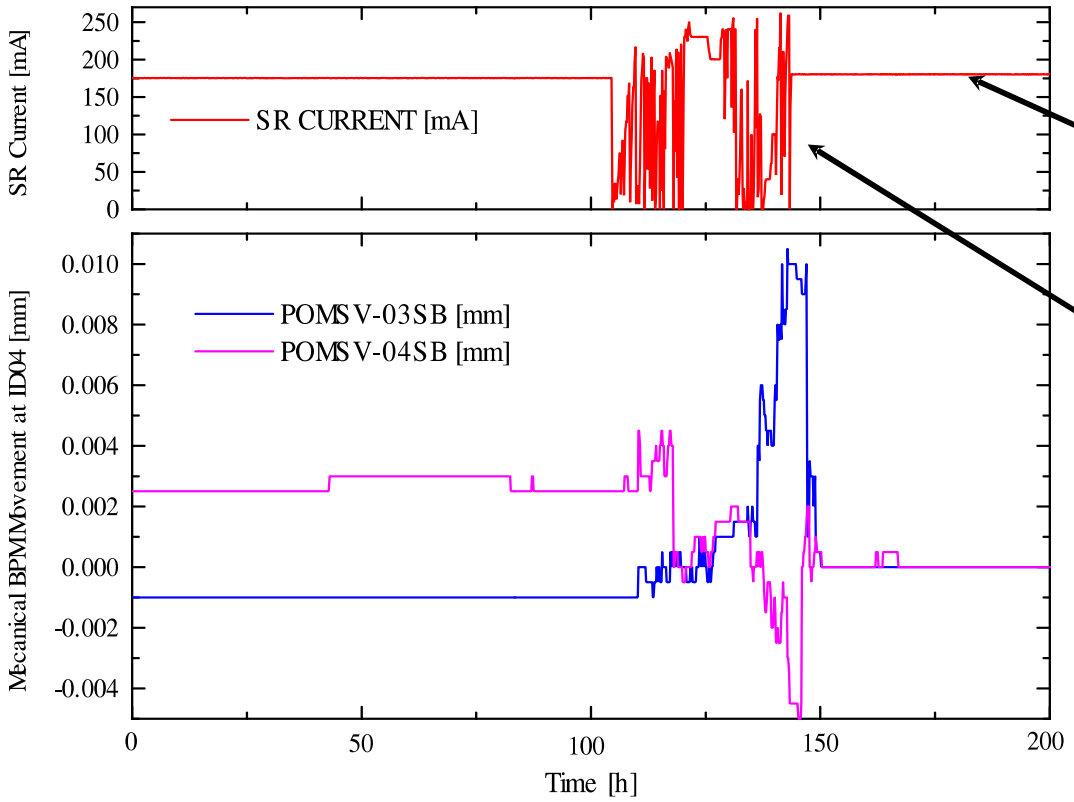
Dial gauges equipped with linear encoders as sensing devices attached to quadrupole magnets





# Stability and Dynamic Alignment at SLS

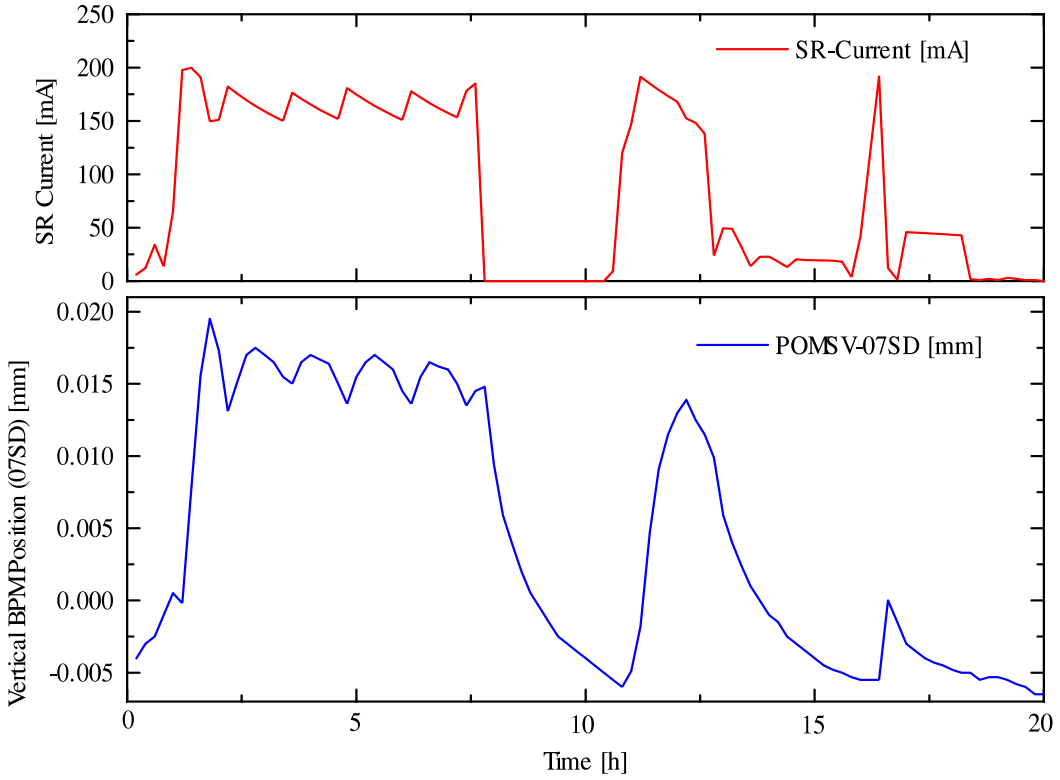
## Vertical BPM Motion at ID-04 as a Function of SR Current




"Top-up" operation of SLS storage ring

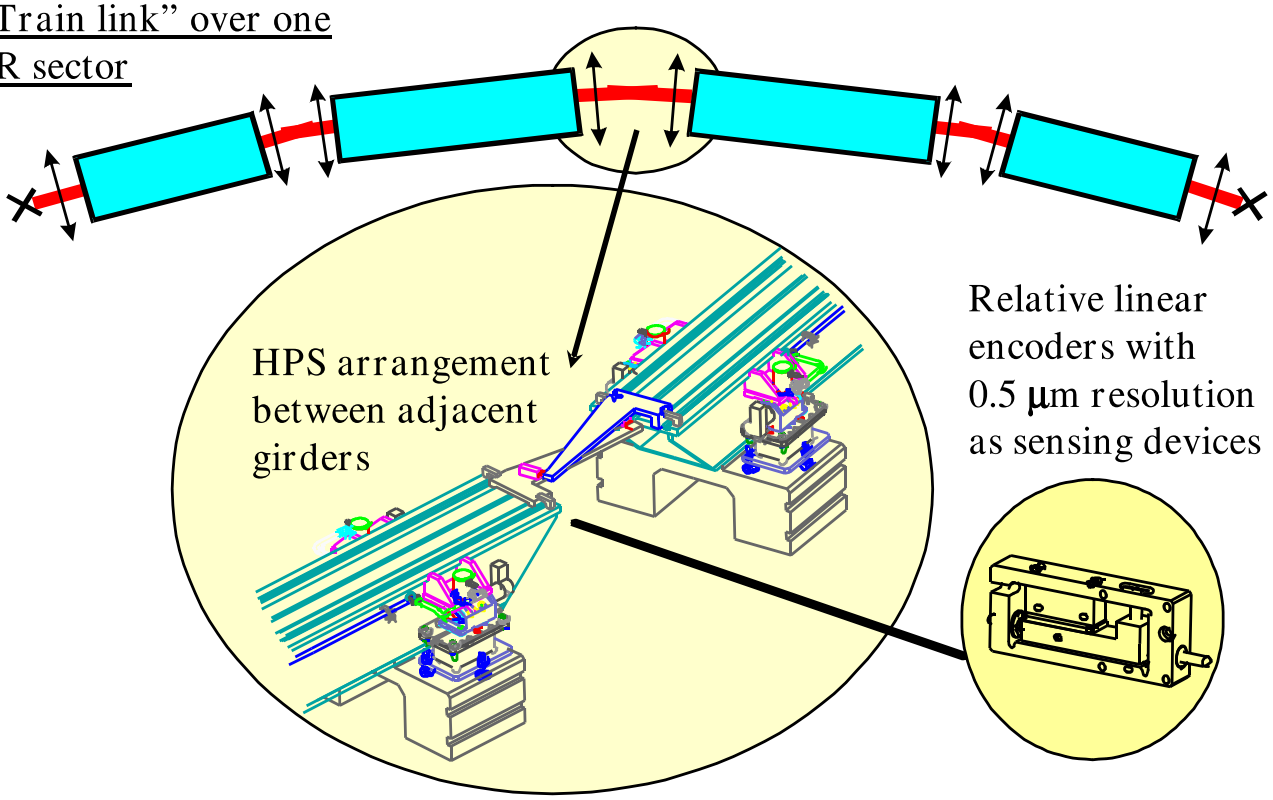
"Beam development" shifts with transient beam current

## Vertical BPM Motion at Bend-07 as a Function of SR Current

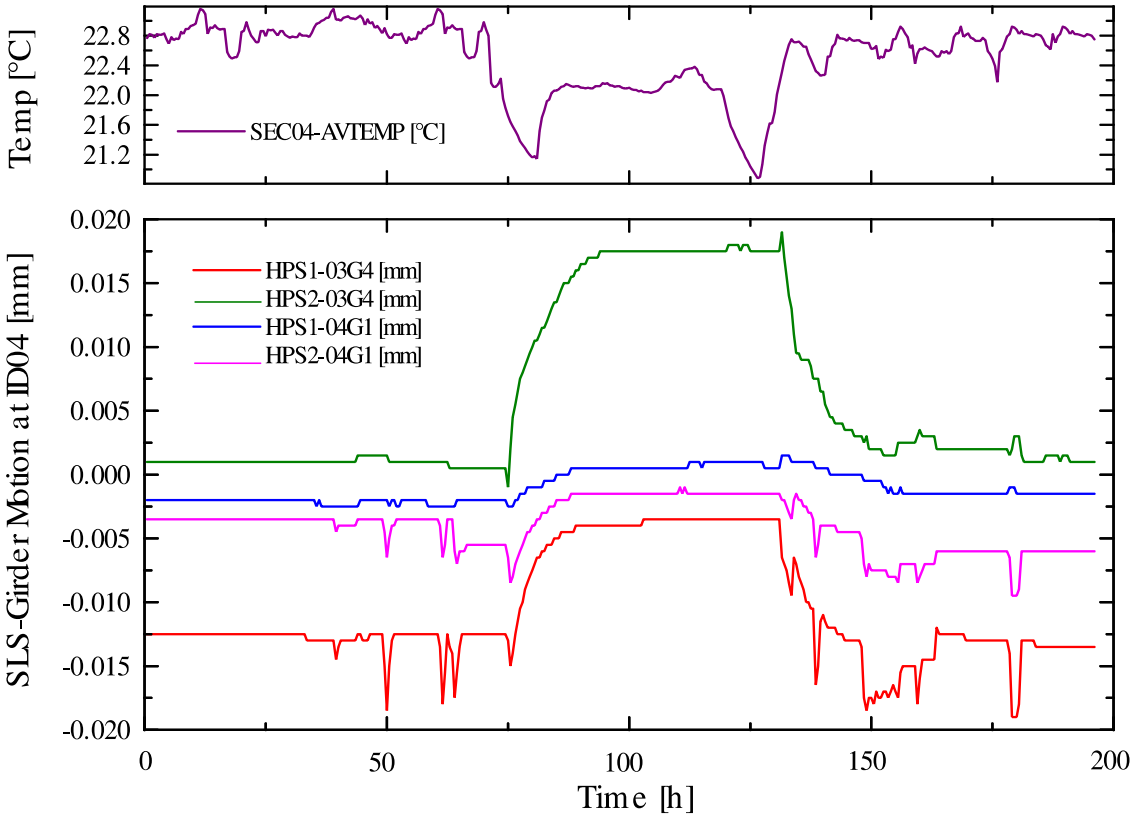


# Horizontal Positioning System (HPS) for SLS Girders

"Train link" over one SR sector




## Girder Motion at ID04 as a Function of SR Tunnel Temperature



# Risoluzione vs. Data Rate

Resolution

[μm]

100

10

1

0.1

Current BPM;
Close Orbit mode

Current BPM;
FEEDBACK mode

Low Gap BPM:
turn-by-turn
***864ns/reading***

Transverse Feedback
***2ns/reading***

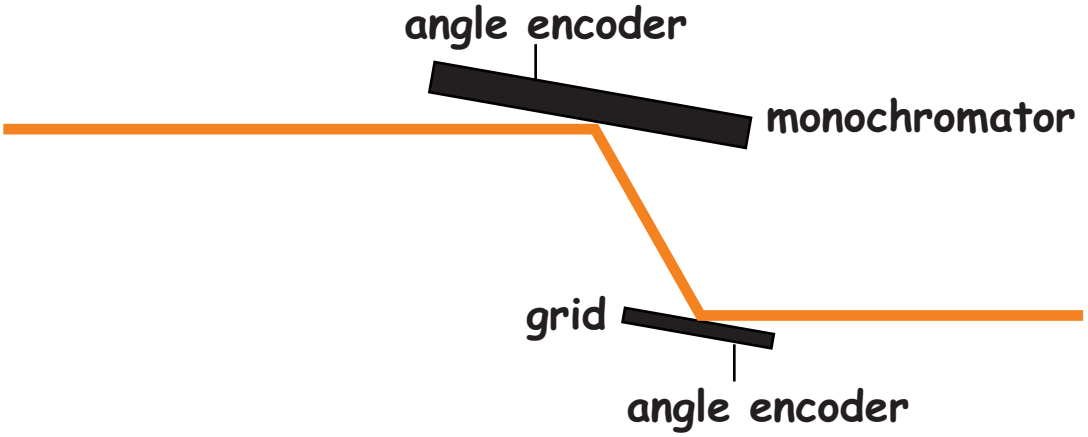
Low Gap BPM
FEEDBACK mode

***89nm,measured on the beam***

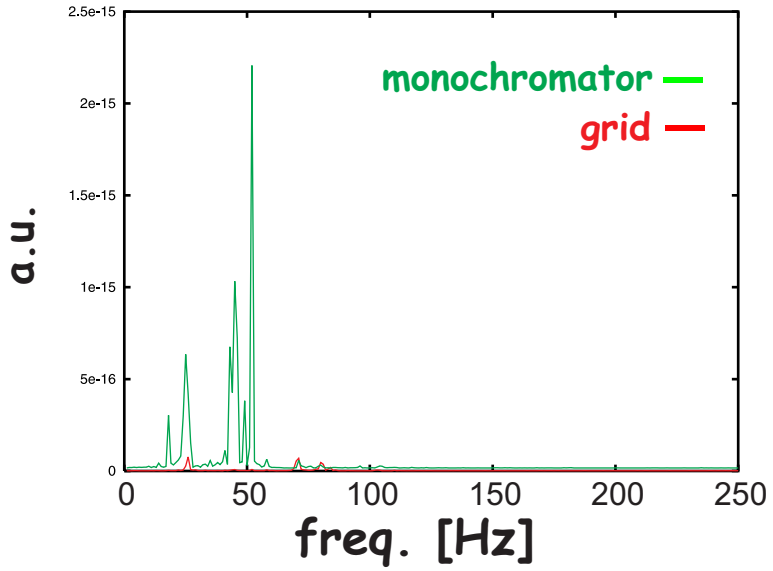
s ms s ns $T_{acquisition}$

# Vibration Damping at the Experiments

- separate noise contributions from
  - electron beam
  - mirrors and monochromators
  - experimental stations




spectrum:




(J. Krempasky)

⇒ passive / active damping of noise sources at experimental setups