



# Slow Orbit Correction in the SPring-8 Storage Ring

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*on behalf of*

**“Beam Orbit Stabilization Project Team”**

**SPring-8**

- 1) Brief History**
- 2) Beam Position Monitors (BPMs)**
- 3) Steering Magnets (STs)**
- 4) Current Status**
- 5) Summary**



## Brief History

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**Beam Commissioning Started in March, 1997.**

**Suppression of Main Harmonics of COD around Tune**

**Calibration of BPMs with Beam:**

**Imbalance of Voltage from Four Button-Pickups**

*M.Masaki, et.al. Proc.11th Symp. on Acc. Sci. and Tech. 1997, p.83*

**Offset by Using High-Harmonic Components**

*K.Soutome, et.al. NIM A459 (2001) 66*

**Direct COD Correction w/o Main Harmonics**

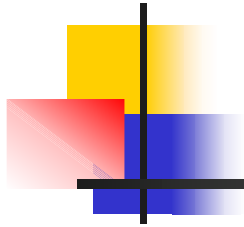
**Minimum Distortion of Dispersion Function**

**Compensation of Energy Drift (Tidal Effect)**

**Averaging of BPM Data on VME**

**“High-Precision” STs**

**(first installed in January, 2001 and added in August, 2002)**



## Number and Position of BPMs and STs

### BPM

**Total Number: 280**

**6 BPMs / Cell**

### ST (“Normal” Type)

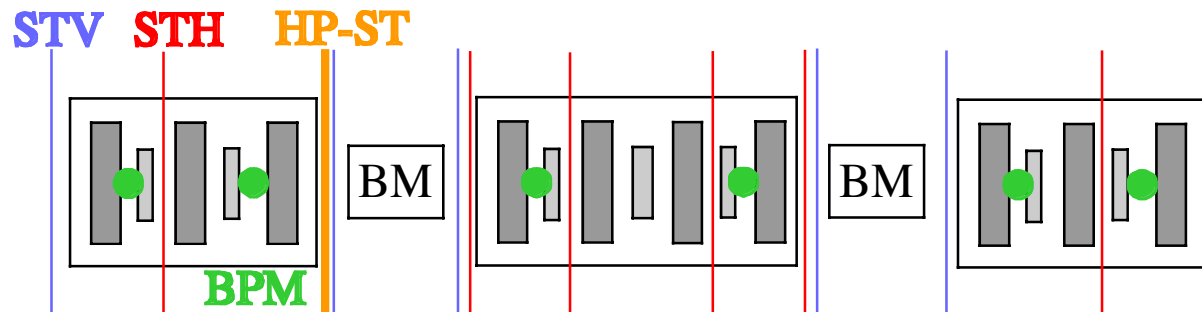
**Total Number: 282(H) ; 268(V)**

**6 STHs & 6 STVs / Cell**

### ST (“High-Precision” Type)

**Total Number: 24(H) ; 24(V)**

**1 STH & 1 STV / 2 Cells**

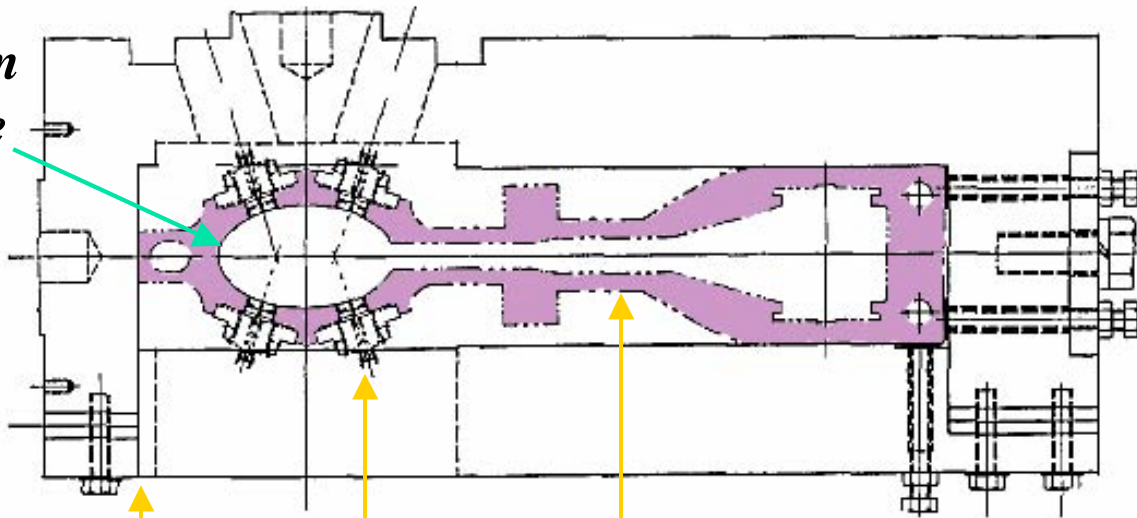




# BPMs for COD Measurements

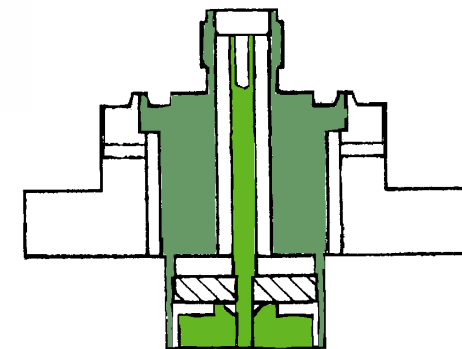
## Cross Sectional View of a BPM Section

70mm  
\*40mm  
Ellipse

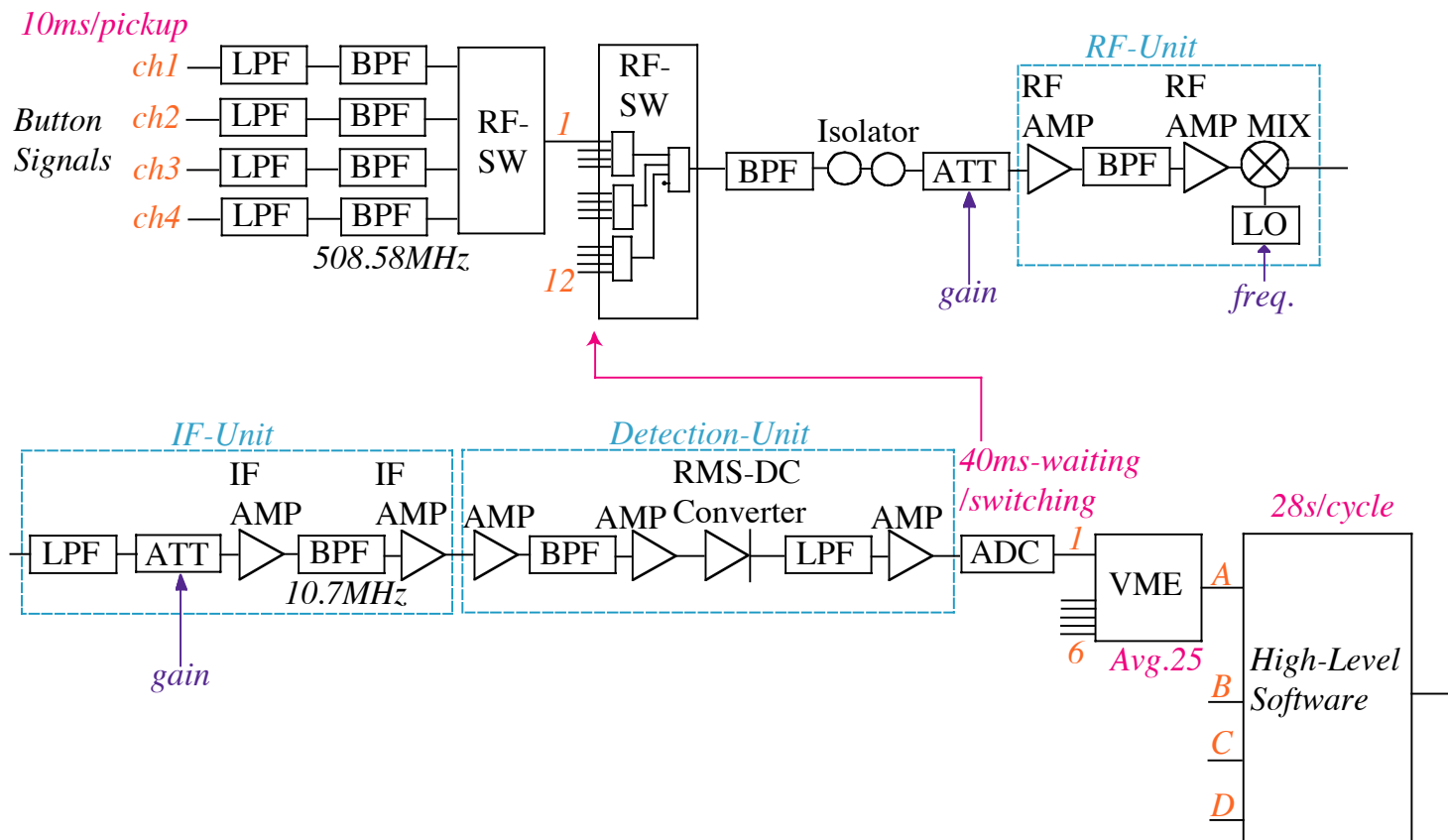


Support    Electrode    Vacuum Chamber

Electrode



# BPMs for COD Measurements (cont.)



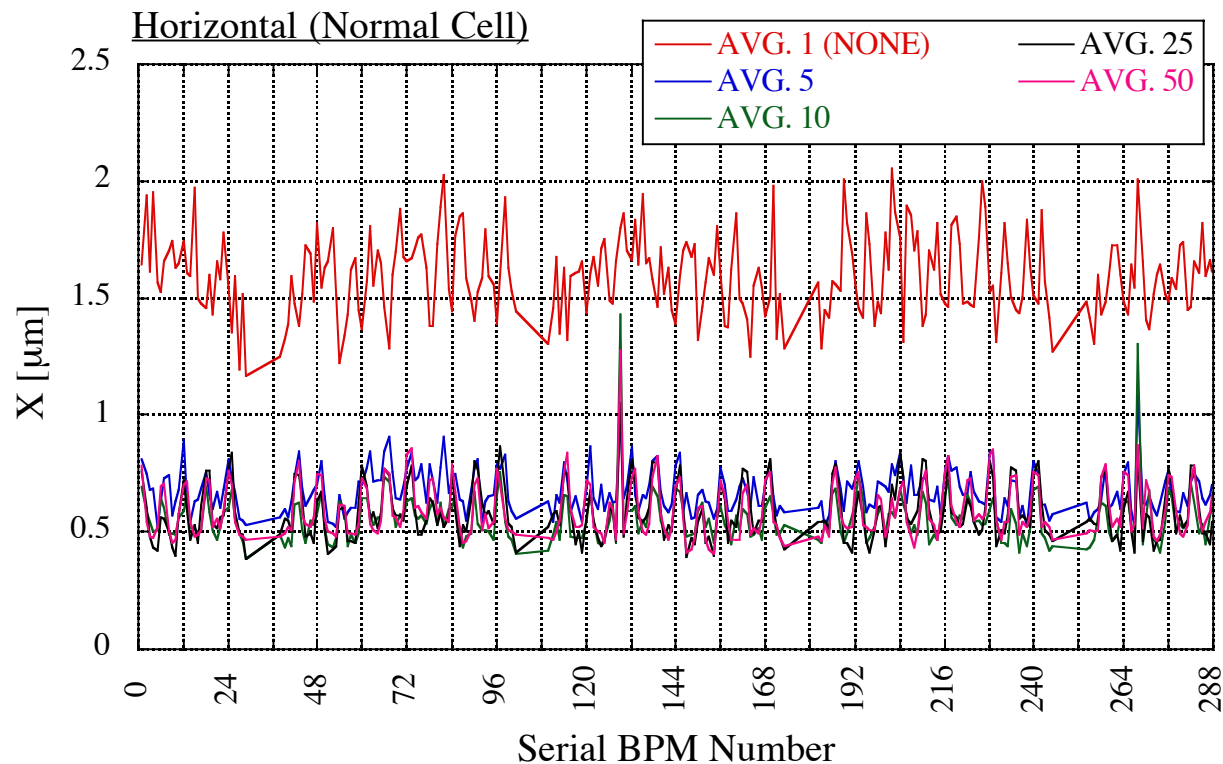
**28sec for a Sequence of COD Measurement (Avg. 25)**

# Reproducibility of BPMs

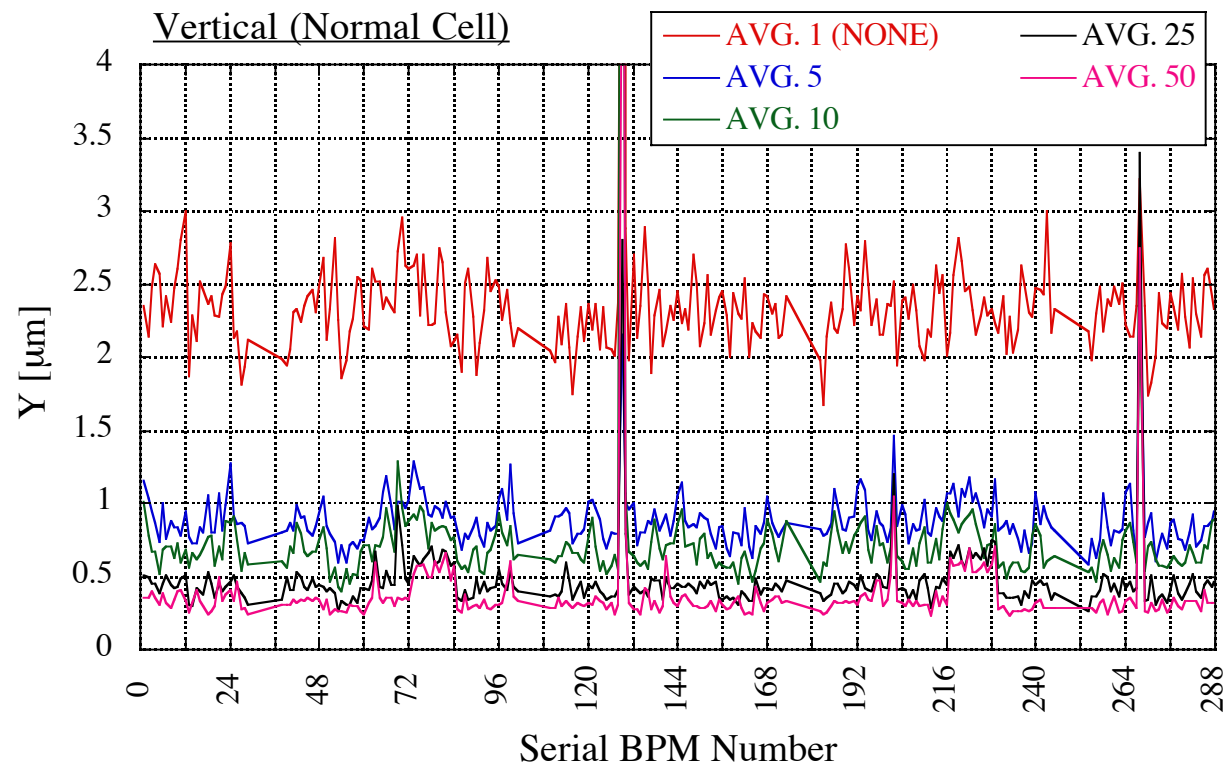
Measure COD repeatedly about 100 times.

→ RMS difference of nearest two CODs

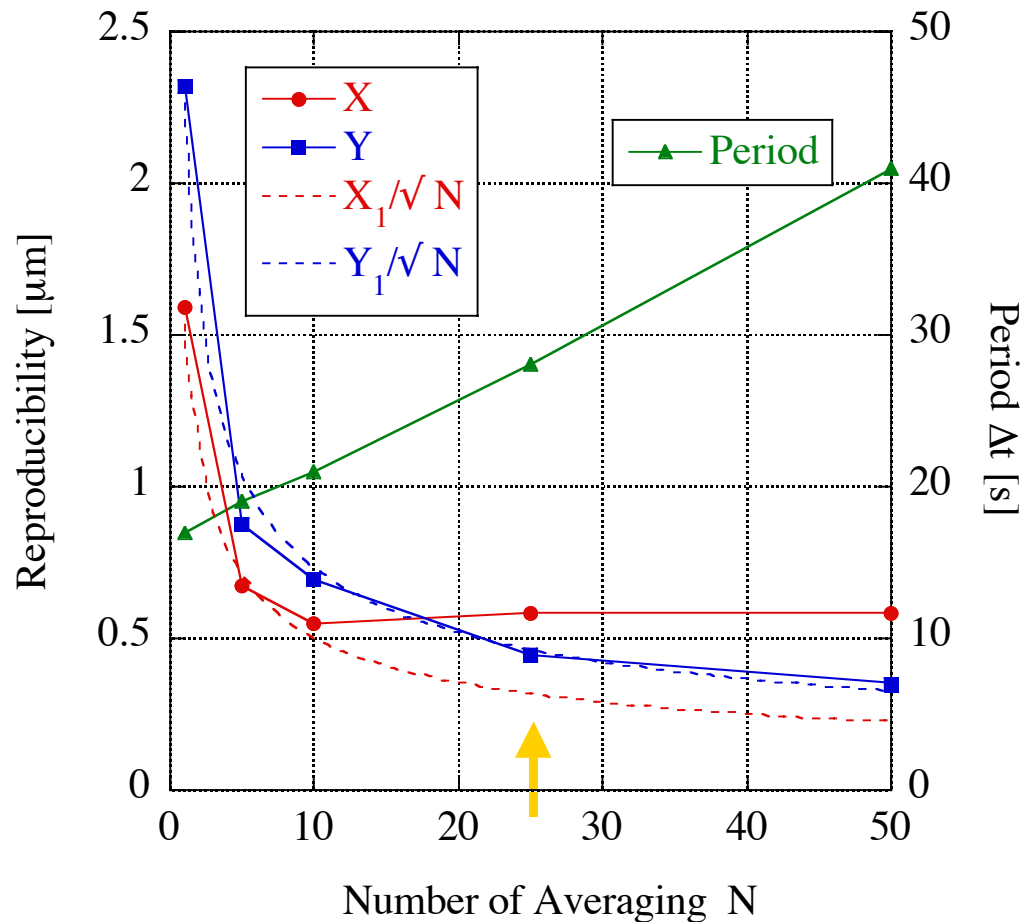
→ **Reproducibility:**  $[\text{COD}(t+\Delta t) - \text{COD}(t)]_{\text{RMS}} / \sqrt{2}$



## Reproducibility of BPMs (cont.)



# Resolution of BPMs



**Resolution Estimated from  
Reproducibility:  
better than  
 $0.6\mu\text{m}(\text{H}); 0.5\mu\text{m}(\text{V})$   
for  $N = 25$**

**Note: The effect of real orbit  
drift within  $\Delta t$  is included.**





## Two Kinds of Steering Magnets

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### “Normal” Type with Iron-Yoke

**Total Number:** 282(H) ; 268(V)  
**Max. Kick Angle:**  $\pm 1$  mrad (H) ;  $\pm 0.5$  mrad (V)  
**Power Supply:**  $\pm 5$  A, 16bit  
**Min. Step:**  $0.03$   $\mu$ rad (H) ;  $0.015$   $\mu$ rad (V)  
... used in manual correction for e.g. beam tuning

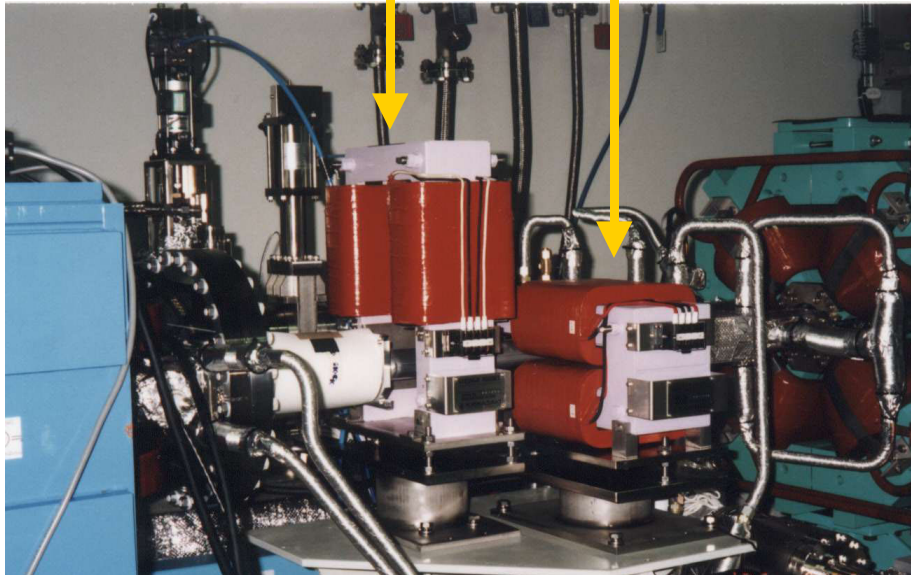
### “High-Precision” Type with Air-Core

**Total Number:** 24 (H); 24(V)  
**Max. Kick Angle:**  $\pm 13$   $\mu$ rad  
**Power Supply:**  $\pm 5$  A, 16bit  
**Min. Step:**  $0.0004$   $\mu$ rad  
... used in auto-correction for user time  
**Hysteresis-Free**

## Two Kinds of Steering Magnets (cont.)

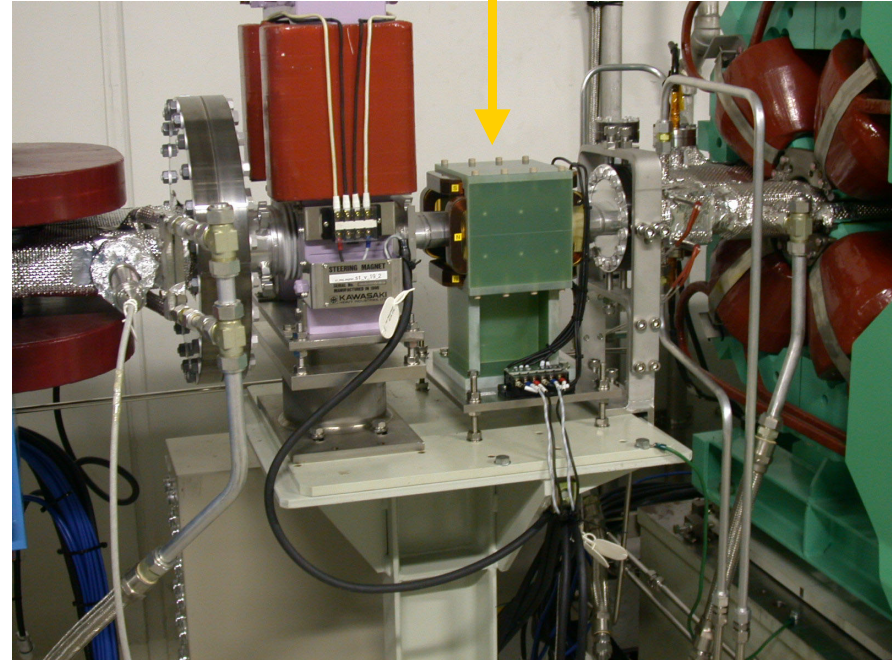
**“Normal”**

**V**      **H**

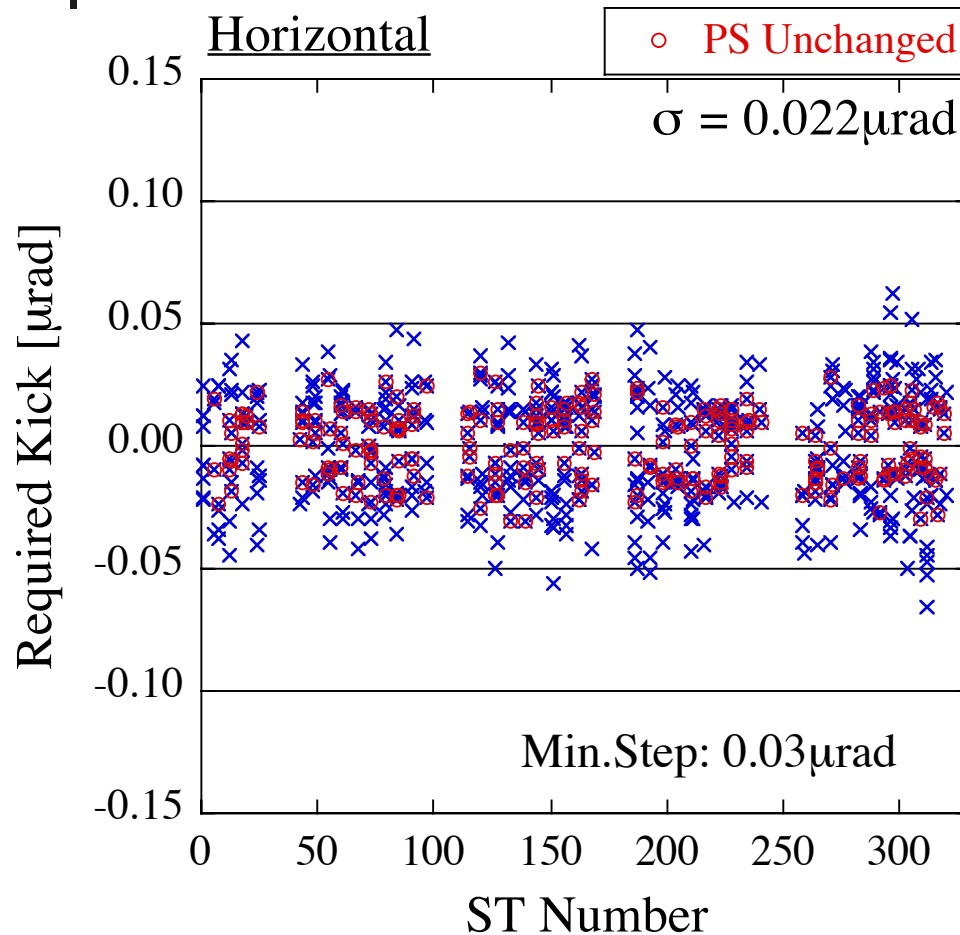


**“High-Precision”**

**H/V**



# Why “High-Precision” STs in User Time?

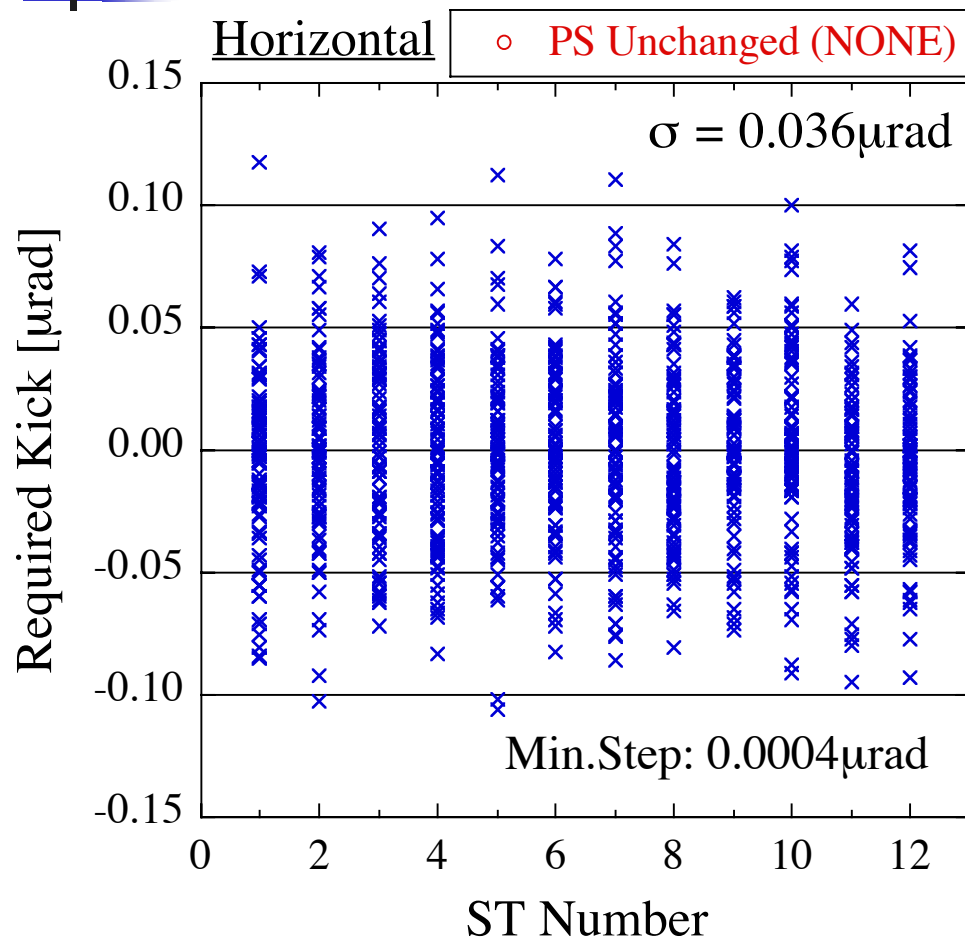


## COD Correction with “Normal” ST

“Best-Corrector” Method  
12 STs Used  
Interval: 40s  
50 Corrections

← Jump of a few  $\mu\text{m}$  order was observed at each correction!

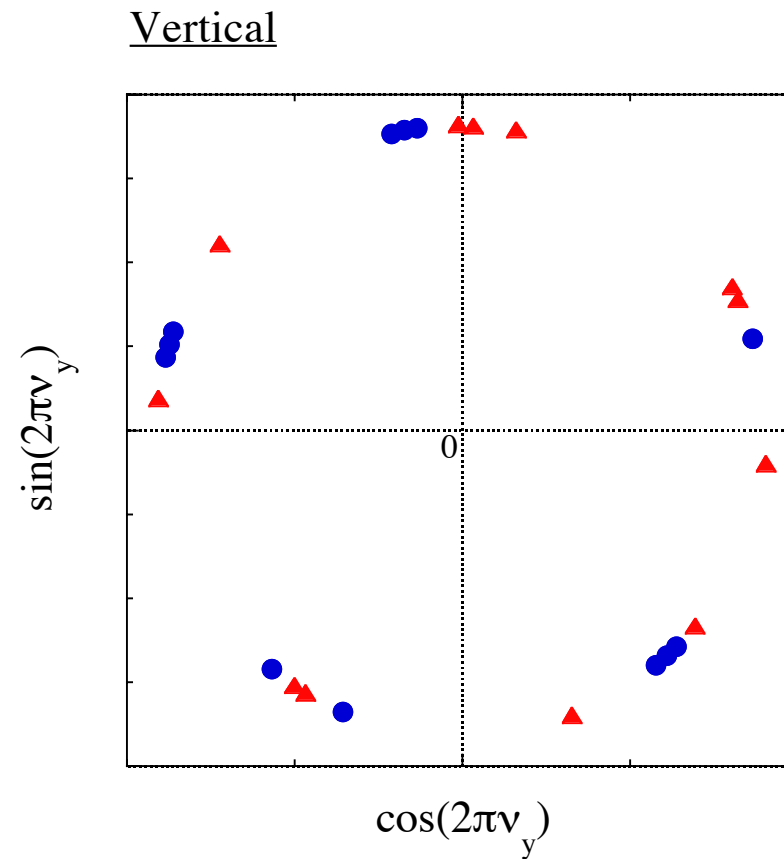
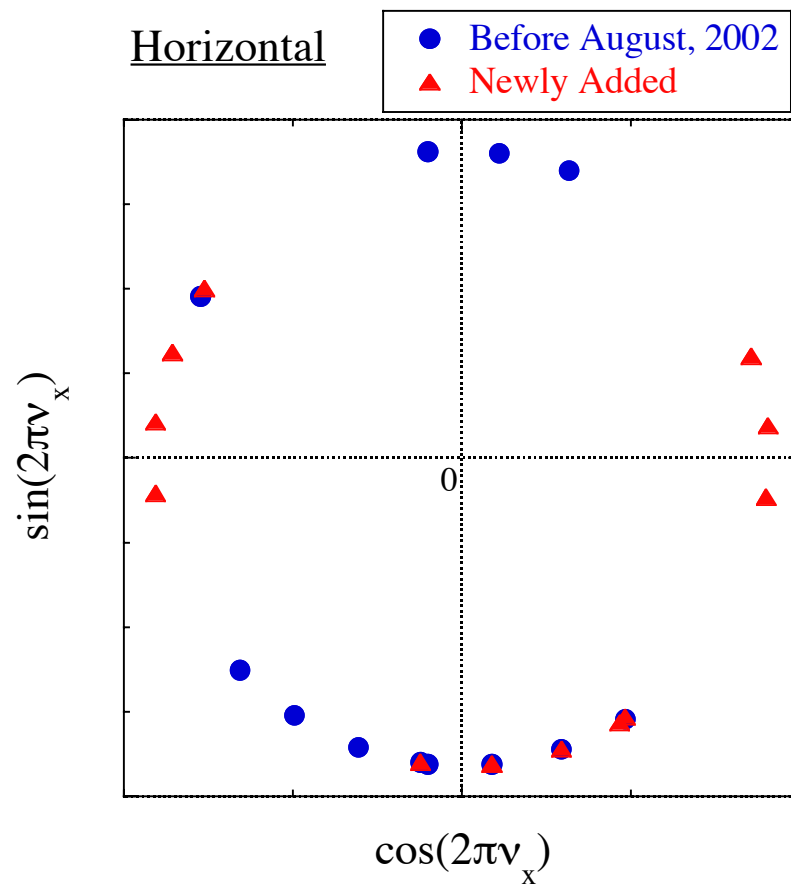
## Why “High-Precision” STs in User Time? (cont.)



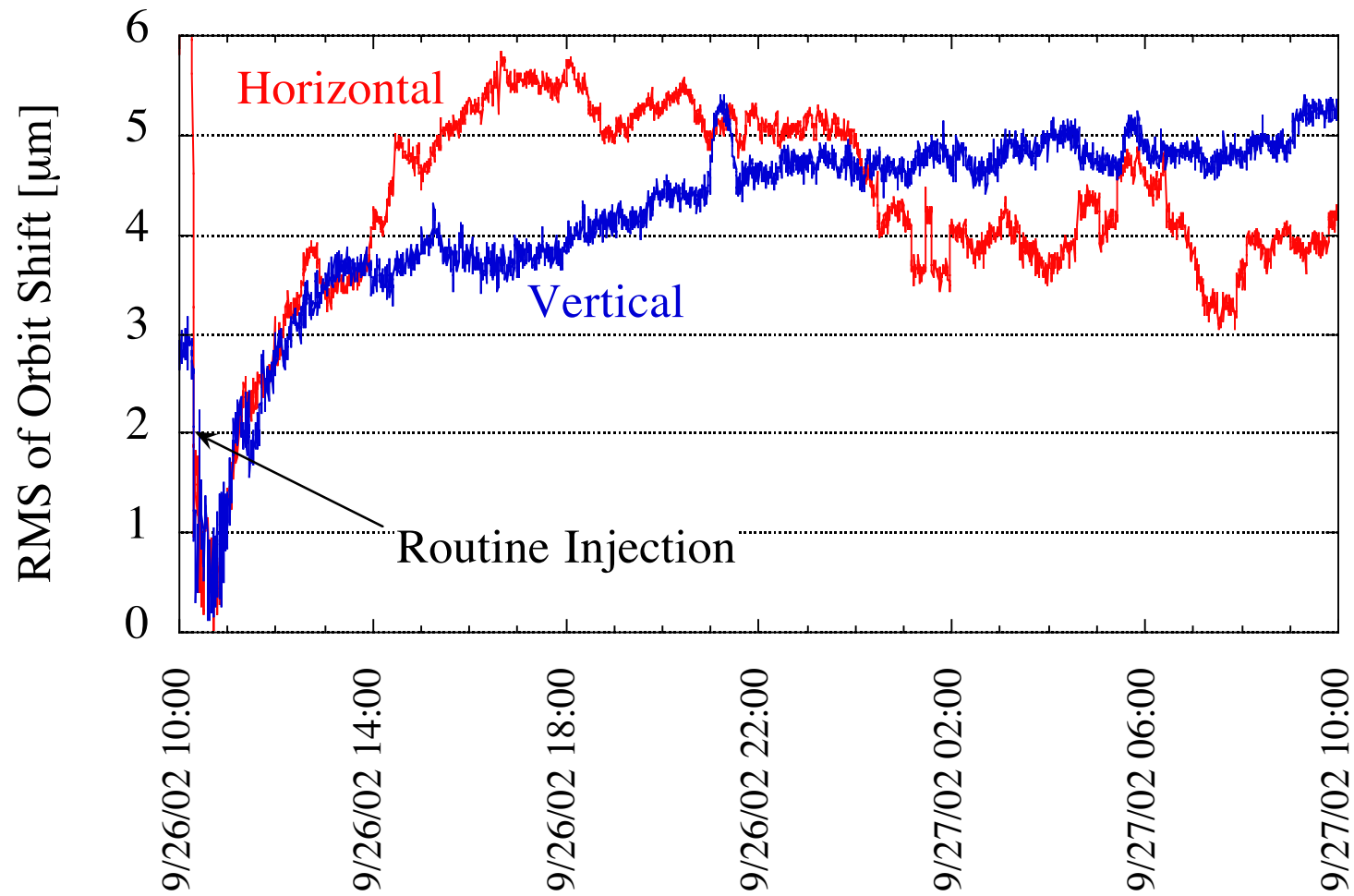
**COD Correction with  
“High-Precision” ST**

← Smooth Correction

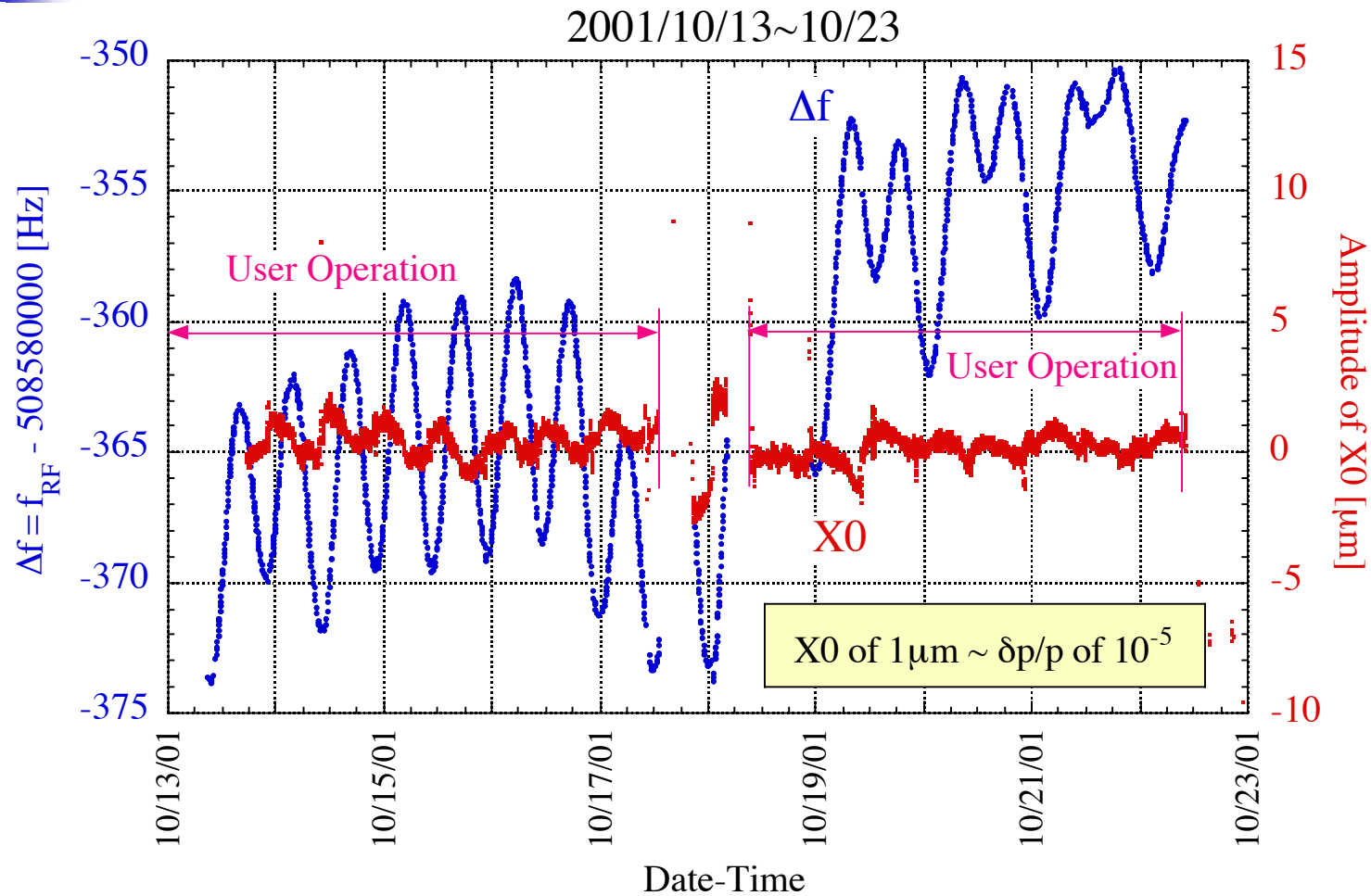
# Betatron Phase at High-Precision STs



# COD Correction - RMS Deviation/Day -



# Compensation of Energy Drift





# Summary

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## BPMs

**Averaging on VME: 25 times**

**Resolution: better than  $0.6\mu\text{m(H)}$ ;  $0.5\mu\text{m(V)}$**

## Steering Magnets

**Two Types of Steering Magnets**

**“High-Precision” Type for Smooth Correction in User Operation**

## COD Correction

**Direct Correction w/o Main Harmonics (Drift  $< 5 - 6 \mu\text{m/day}$ )**

**Compensation of Energy Drift by RF Frequency ( $\Delta p/p \approx 10^{-5}$ )**