Workshop on Stability of Beam Orbit in Accelerators:

Brownian Ground Motion And Dynamic Alignment of the Accelerator

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- Power Spectrum Density and Coherence
- Slow Ground Motion and Geology
- Slow Ground Motion and Excavation Methods

		X-band	C-band	
Beam Energy Entrance/Exit	E0/E1	10/500	10/500	GeV
Particles/bunch	Ν	0.8	1.0	1010
Invariant Emittance	$\boldsymbol{\varepsilon}_{N_y}$	30	30	nm
Bunch length	σ_{z}	80	200	μm
β at entrance	${m eta}_0$	4	4	m
Rf frequency	f	11.4	5.7	GHz
Accel. gradient	dE/ds	45	32	MeV/m
Iris radius/wavelength	a / λ	0.16	0.14	
ATL coefficient	Α	1	1	nm²/s/m
Stable time for $\in =0.1$	t	3	24	hours

Typical Parameters of Linear Collider

Brownian Ground Motion and Dynamic Alignment of the Accelerator

Sensors for Studies









(1)

Empirical Continuous Power Spectrum Density;

$$P(f) = \frac{K}{4\pi^2 f^2 (f_0^2 + f^2)},$$

 f_0 : 0.1Hz - 0.01Hz In the hard rock region: $f_0 \approx 0.1$ Hz $f = f_0 P(f) = K/f^2$

Brownian motion of rocks becomes dominant *K* strongly depends on the site

The ATL model:

Formulation using an auto-correlation function $\langle y(t+\tau)y(t) \rangle$

$$\Delta y(\tau)^2 = 2 < y(t)^2 > -2 < y(t+\tau)y(t) > = A \cdot L \cdot \tau.$$
(2)

< X >: an ensamble average

Definition of a Power Spectrum;

$$P(f) = \int_{-\infty}^{\infty} \langle y(t+\tau)y(t) \rangle e^{-2\pi i f \tau} dt d\tau , \qquad (3)$$

$$A \cdot L \cdot \tau = 4 \int_{-\infty}^{\infty} P(f) \sin^2(\pi f \tau) df .$$
 (4)

 $[f = f_0]$

 $4\int_{-\infty}^{\infty} P(f)\sin^2(\pi f\tau)df = K \cdot \tau$ (5)

Power Spectrum of ATL model as,

$$P(f) = \frac{A \cdot L}{4\pi^2 f^2}.$$
(6)

[Actual Experiment]

$$P(f) = \frac{K}{4\pi^2 f^2 + (1/\tau_{\rm max})^2} , \qquad (7)$$

$$1/\tau_{\rm max}$$
 : cutoff frequency

The Integration of Equation (5);

$$4\int_{-\infty}^{\infty} P(f)\sin^2(\pi f\tau)df = K\tau_{\max}\left(1 - e^{-\tau/\tau_{\max}}\right).$$
(8)

$$\Delta y(\tau)^2 = A \cdot L \cdot \tau_{\max} \left(1 - e^{-\tau/\tau_{\max}} \right). \tag{9}$$



Recently, many accelerator physicists use ATL model for their accelerator simulation because of simplification of the calculation. But we have to take account of **applicable limitations in the light of coherency of the ground motion spectrum.**



No	Site Name	A (nm²/m/sec)	Geology of the Site
1	Tunnel of KEKB	4.0E+01	Clay and Gravel
2	Rokkoh-1	3.6E+01	Granite (near Fault)
3	Rokkoh-2	3.3E+01	Granite
4	Miyazaki	1.5E+01	Diorite
5	Spring-8	8.0E-01	Granite
6	Kamaishi-1	1.4E-01	Granite (Crack and Water)
7	Kamaishi-2	5.7E-02	Granite
8	Sazare	5.0E-02	Green Schist
9	Esashi-1	5.7E-03	Granite (Floating Stone)
10	Esashi-2	2.0E-03	Granite

ATL COEFFICIENT in JAPAN

Geological Map of Japan and the Related Sites for ATL Table. Described numbers are the same in figures and Table.

Coherence-1



Ground motion in the noisy site (KEK). Coherence between two points at a distance of 48 m. Power spectra for the two points are the same. Incoherent spectrum is given by the equation shown in the figure. A big bump spectrum, around 0.2 Hz, corresponds to the ocean swell. The incoherent spectrum around 3 Hz comes from traffic noises. This incoherent vibration gives an amplitude of 83 nm. That is, the tunnel in KEK should have a depth of 900 m, providing we want the amplitude of 1 nm.









The time series data on the vertical ground motions observed at three points being 14 m apart between one another.





Coherence in the Granite Tunnel Having a Floating Lumped Rock.

Except the #1 lumped rock position, we get good coherence.

#1 shows no earth-tide spectrum. *ATL* coefficient in this point is a little bad as shown in the previous *ATL* Table.

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Kamaishi





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9903

frequency (Hz)

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Coherence-2



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What Happen in the Tidal Frequency

Conclusion



Detail drawing of the vertical active mover.

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Conclusion

架台の共振点:

- X 軸方向: 5.8Hz、12.5Hz、16Hz、29Hz、 Y 軸方向: 12~16Hzのブロード共振、30Hz、90Hz、
- Z 軸方向: 2.3Hz、5.6Hz、8Hz、80Hz、

ガーダーのクリープ特性と高剛性化

- 加速管: 長さ 1.8m
 - **重量** 250kg
 - 使用数 8,000 台
 - **設置精度** 30 µ m

ガーダー及び調整機構は3µm以下の確度で再現性

コンクリートパイルの鋼板巻きの低価格ガーダーは、そのクリープ特性の評価 が製作条件に強く依存して非常に困難であることが判明 強く伸張したピアノ線材 (PC 鋼棒)をコンクリートで固めた円柱架台 クリープ歪み進行過程の計算:クリープの進行が4µm 以下になるのが製作後 約一年掛かる。

<u>表 - 1 ガーダー材料の諸元</u>

材料	断面積	断面2次モーメント	ヤング	単位長重
	(cm ²)	(cm^4)	率	皇
			(ton/cm ²)	(kg/m)
PC 杭:600 , t=90	1,473	493,415	410	375
角形コラム:600 , t=16	363	203,000	2,100	285
RC:600	3,600	1,080,000	210	864

PC 杭は肉厚 90mm の円筒状とし、9 の PC 鋼棒 12 本を一様に配置した。

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モード次数	1次	2次	3次	4次	5次
モード形状	Y	Z	х	弾性モード	弾性モード
PC 杭	5.0	5.8	7.0	33.8	228.0
角形コラム	5.0	5.8	7.0	51.6	355.9
RC	5.0	5.9	7.1	26.7	175.7

以上から、RC 杭方式の代わりに、PC 杭を使う方が LC のガーダーとして有効であることが分かった。残る問題で解決せねばならないことは、

1) PC 杭方式の方が RC 杭方式に比べて、製作費が3.5 倍になること、

2) 5 HzのY 方向振動に対するダンパーが必要なこと、

3)ガーダーの重量が3トンと重くなり、その分能動駆動機構の負荷が大きくなる。



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Conclusion



- It is essential to search the site being $A < 1 \text{ nm}^2/\text{m/sec}$ for the long term stability of the alignment.
- TBM is the best solution for cutting the tunnel of LC.
- The separated tunnel is preferable to suppress the noises in the accelerator tunnel caused by the accelerator facility.
- We have to pay attention to local fluctuation of the *ATL* coefficient and the coherence around the betatron wave length for the construction of the long scale LC.