#### Beam-Stability Issues in the KEKB Injector Linac

T. Suwada

Accelerator Laboratory,

High Energy Accelerator Research Organization (KEK), 1-1 Oho, Tsukuba, Ibaraki 305-0801, Japan

#### **KEKB** Accelerator Complex



#### Layout of the KEKB Injector Linac



#### **Operation Log** of the KEKB e<sup>-</sup>/e<sup>+</sup> Beam Currents



#### **Typical Beam Parameters for** the KEKB Injection

Parameters	e <sup>-</sup> @BT	$e^+$ @BT	$e^{-}/e^{+}$
Energy [GeV]	8.0	3.5	3.7 <sup>1)</sup>
Charge [nC]	$0.8/1^{*}$	$0.4/0.6^{*}$	$8.0^{1)}$
$\Delta E/E [\%@1\sigma]$	0.05	0.15	$0.5^{2}$
$\gamma \epsilon_x / \gamma \epsilon_y \ [mm@1\sigma]$	0.31/0.31	2.4/2.0	$3.5/1.8^{3}$
<b>Injection Rate</b>	4	1.8	
[mA/s]@50 Hz	(>95%)	(>95%)	

The symbol "\*" shows the parameters measured at the end of linac, and subscripts 1), 2) and 3) depict the parameters at the positron target, at the center of the J-arc line, and at the end of the sector B (E=1.7 GeV), respectively.

#### **KEKB** Operation

- *Stable high injection* rates were performed by
- (1) *dedicated beam* and *rf feedback systems*, and
- (2) daily monitoring of the *optics matching* and *beam emittances*, and the *energy spread of the beams* by wire scanners, and fine injection tuning.
- Beam and rf feedback systems have been stably operated
- (1) for *beam orbits* and *beam energy*, and
- (2) for the *pre-injector*.





#### Schematic layout of the pre-injector

Element	<b>Repetition or</b>	-	Voltage or
	Frequency	period	Power
Grid pulser	1~50 Hz	-	450~800 V
Gun	50 Hz	-	200 kV
25 <sup>th</sup> SHB1 (standing wave)	114 MHz	8.75 ns	11 kW
5 <sup>th</sup> SHB2 (standing wave)	571 MHz	1.75 ns	7 kW
Prebuncher (travelling wave)	2856 MHz	350 ps	1 MW
Buncher (travelling wave)	2856 MHz	350 ps	23 MW
Accelerating sections (travelling wave)	2856 MHz	350 ps	12 MW x 2
Common frequency of linac/KEKB rings	10.385 MHz	96.289 ns	-

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#### **Pre-Injector System: Feedback System**



#### **Pre-Injector System: Temperature** Variation in Gun Room



# **Pre-Injector System: Phase Stability** of SHB1, 2 & Buncher



### **Pre-Injector System: Variation of Grid-Pulse Timing**



# **Pre-Injector System: Variation of Beam Timing**

![](_page_11_Figure_1.jpeg)

#### Control & RF Feedback System of the Gun Beam

	Tolerance	Stability	FB	Remraks
Gun High Voltage [%]	±0.38	~0.05	ON	200kV
Gun Beam Timing [ps]	±45	20	ON	
SHB1 RF Power [%]	-	~1	ON	114.2MHz/11kW
SHB1 Phase [deg.]	±1.1	0.5	-	
SHB2 RF Power[%]	-	~1	ON	571.2MHz/7kW
SHB2 Phase[deg.]	±1.3	1.0	-	
Buncher Power [%]	±0.47	~1	-	2856MHz/~23MW
Buncher Phase [deg.]	±1.7	±1.0	-	

#### **Optical-Transition Monitor**

![](_page_13_Picture_1.jpeg)

#### Bunch Profile Measurement Using OTR Monitor

![](_page_14_Figure_1.jpeg)

#### **RF** Stability:Main Drive System

メインドライブシステム

![](_page_15_Figure_2.jpeg)

#### Stability of RF: Trend Graphs

Phase Stability of 114,571 & 2856MHz Master Oscillators

![](_page_16_Figure_2.jpeg)

# Stability of RF: Monitor System

#### **RF MONITOR SYSTEM**

![](_page_17_Figure_2.jpeg)

#### Stability of RF:Trend Graphs

![](_page_18_Figure_1.jpeg)

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#### **Beam Feedback Systems**

![](_page_19_Figure_1.jpeg)

## Typical e<sup>+</sup> Beam Orbits & Charge for the KEKB Operation

![](_page_20_Figure_1.jpeg)

#### Beam Orbit & Energy Stability: Beam-Position Monitor

![](_page_21_Picture_1.jpeg)

![](_page_22_Figure_0.jpeg)

# Beam Energy Stability: Control Panel

- R0 Energy Feedback				
File	R0 Energy Feedback		17:48 v1.6.2	
get command (source) lindex [set sptem] acquisition interval (sec) 1. current source 1.04 avarage count 2 averaged source 0.645 minimum -12 maximum 15 Satisfied	loop interval (count) 1 offset 0 difference 0.645 gain -0.001 feedback -0.000645	get command (condition) lindex \$sptemp 2 minimum 0.2 value 6.47 Satisfied	get command (target) energy2_get r0 current target 1.61849259611 new target 1.61794759611 minimum 1.5 maximum 1.5 Satisfied put command (output) energy2_set r0	
Start		Stop	Beam Condition	

## Beam Energy Stability: Trend graphs

![](_page_24_Figure_1.jpeg)

# Beam Orbit Stability: Principle of Feedback

#### **Other Feedback Loops**

Simple Orbit Feedback

Monitor: Weighed Average of BPM's over 1 Betatron Wavelength Tuner: Two Steerings with 90-degree phase advance (Difficult to Predict Orbit Because of Wake Fields)

![](_page_25_Figure_4.jpeg)

# Beam Orbit Stability: Trend Graphs

![](_page_26_Figure_1.jpeg)

#### Beam Optics Stability: Wire Scanner

![](_page_27_Picture_1.jpeg)

## Beam Optics Stability:Measurement Using Four Successive WSs

![](_page_28_Figure_1.jpeg)

# Beam Optics Stability: Optics Matching

![](_page_29_Figure_1.jpeg)

#### Beam Optics Stability: Daily-Logged Parameters

![](_page_30_Figure_1.jpeg)

#### Beam Optics Stability: Daily-Logged Parameters

![](_page_31_Figure_1.jpeg)

#### **Energy Spread Stability: Energy Spread Monitor by WSs**

![](_page_32_Picture_1.jpeg)

#### **Energy Spread Stability: Daily-Logged Parameters**

![](_page_33_Figure_1.jpeg)

#### **Energy Spread Stability: Daily-Logged Parameters**

![](_page_34_Figure_1.jpeg)

### Beam Trajectory Jitter Analysis (Jitter Emittance)

![](_page_35_Figure_1.jpeg)

#### Beam Trajectory Jitter Analysis (Blow up of Jitter Emittance)

![](_page_36_Figure_1.jpeg)

# Beam Trajectory Jitter Analysis (βFunction Measurement)

![](_page_37_Figure_1.jpeg)

# Beam Trajectory Jitter Analysis (β Mismatch Parameter)

![](_page_38_Figure_1.jpeg)

![](_page_39_Figure_1.jpeg)

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# **Beam-Energy Stability: Step Variation Detection Algorism Using an E-Filter**

![](_page_40_Figure_1.jpeg)

![](_page_41_Figure_1.jpeg)

![](_page_42_Figure_1.jpeg)

![](_page_43_Figure_1.jpeg)

# **Conclusions**

#### ♦ Daily Operation

It has been almost established for the KEKB by

- •Frequent beam diagnosis and check,
- •Dedicated beam and rf feedback systems, and
- •Several-times/month check of machine and instrumentation.
- Systematic Evaluation on the Beam Stability Issues
- It is strongly required to specify origins causing the beam instabilities which need to be investigated by

•three factors, that is, frequency and amplitude of variation, and location.

# Strategic Scheme for the Beam Stability Issues

![](_page_45_Figure_1.jpeg)

# Strategic Scheme for the Beam Stability Issues (cont.)

![](_page_46_Figure_1.jpeg)

# Several Plans in Progress

#### ♦ More Refined Beam Feedback System

•Global orbit feedback/Continuously Controlled orbit Correction(*CCC*)

•Refined energy feedback taking into account the beam optics

#### ♦ More Dedicated Beam Monitors

•Nondestructive energy-spread monitor(ESM)

•Pulse-to-pulse data-acquisition(DAQ) and detection system for BPMs and ESMs

#### More Dedicated Control System

•New DAQ scheme synchronously measuring all data from the monitor, rf, pulsed devices and facility environments.